## **Second Generation of Eurocode 8**

# WEBINAR 4: Silos, tanks, pipelines, towers masts and chimneys – Ancillary elements in industrial facilities

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#### **SCOPE OF APPLICATION**

- Seismic design of **ancillary elements** (non-structural components) attached to structures in industrial facilities
- Not Covered:
  - Components employing isolators, viscous or friction dampers,
  - Components that may respond by sliding or rocking
  - Interaction with other independently attached components
  - Impact with the structure or other components
  - Functioning and process interdependencies
- Covered
  - Non-interacting single-support yielding/elastic components
  - Multi-support components governed by differential support motion

#### WHY OH WHY?

- EN1998-1-2 already includes provisions for non-structural components
- Are we replicating them?
- EN1998-4 is meant for **industrial** facilities
- Different safety standards, different requirements, different modes of application
- Ancillary elements may be upgraded, replaced, or modified through the structures lifetime
- Need flexibility in designing their supports, without necessarily reanalyzing the full structure
- Need **simplicity** in application to accommodate many **safety-critical** components
- Uncertain structural characteristics are they key issue

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#### **BASIS OF DESIGN**

- Design must account for
  - ancillary elements
  - connections to the supporting structure
  - interactions with the supporting structure
- Impact among components or components & structure shall be eliminated by providing adequate clearance
- All partial safety factors per EN1998-1-2
- Ensure **compatibility**!



#### MODELLING

- Model = supporting **structure(s)** + component
  - Single/multi-support components that interact statically or dynamically with the supporting structure(s)
  - Multi-support components sensitive to **both** differential support deformation and vibration
- Model = supporting structural **member(s)** + component
  - Single/multi-support components that interact statically or dynamically with the supporting member(s)
- Model = component only
  - Single-support components without interactions, subject to floor acceleration spectra (= business as usual <sup>(2)</sup>)
  - Multi-support component with negligible vibrations, subject to differential support deformations (= business as usual <sup>(2)</sup>)

#### ANALYSIS

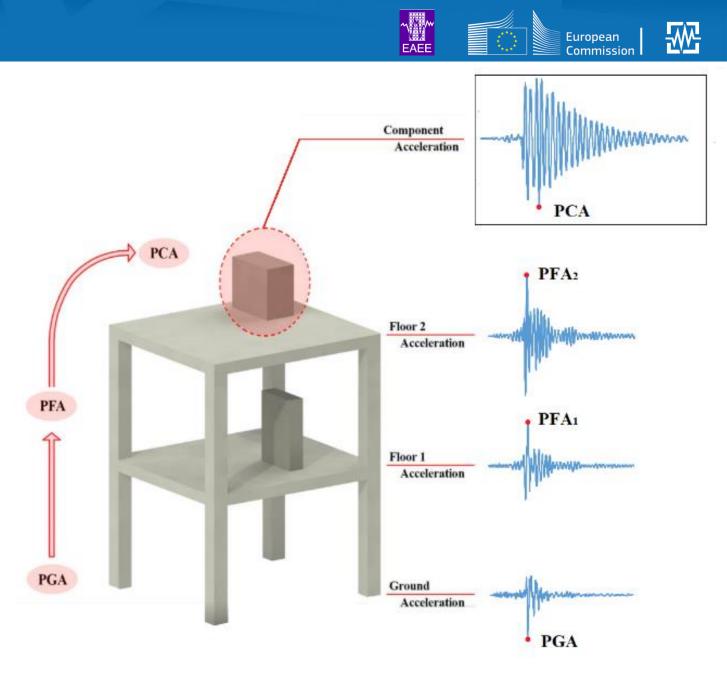
- Model = supporting structure(s) + component
  - Modal response spectrum (MRSA) or response history analysis (RHA)
- Model = supporting structural **member(s)** + component
  - MRSA or RHA
  - Equivalent static analysis (ESA) given component support spectra
- Model = component **only** 
  - MRSA (multi-mode)
  - ESA (single-mode) given component support spectra => Typical case!

#### **Our focus!**

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### FROM PGA TO PCA

- Ground motion is **modulated** by structure
  - PGA becomes PFA
- Floor motion is modulated by element
  - PFA becomes PCA
- Resonance is the enemy
  - Sensitive problem
  - Must know periods of structure & element, damping ratios, inelasticity developed
  - Resonance only happens under perfect tuning & elasticity



### THREE METHODS FOR DESIGN

- Method 1: EN 1998-1-2:2022
  - Non-dissipative (except component behavior factor)
  - Complex & accurate
  - Must know periods, mode shapes, damping ratios, behavior factor(s)
- Method 2: EN 1998-4:2022
  - Non-dissipative
  - Simplified & conservative
  - Imperfect knowledge is assumed -> Resonance assumed
- Method 3: EN 1998-4:2022
  - Dissipative
  - Requires "fuse" with certified overstrength and ductility
  - Imperfect knowledge is ok









#### **METHOD 1: NO CAKE**

- Rinse & repeat for each **mode** of the structure
- Must know periods and mode shapes
- **Damping** determines amplification
- Component & structure behavior factors are important

$$F_{\rm ap} = \frac{\gamma_{\rm ap} \cdot m_{\rm ap} \cdot S_{{\rm ap},j}}{q_{\rm ap}}$$

$$S_{\mathrm{ap},ij} = \frac{T_i \cdot \varphi_{ij}}{\left| \left| \frac{T_{\mathrm{ap}}}{T_{\mathrm{p},i}} \right|^2 - 1 \right|} \sqrt{\left| \left| \frac{S_{\mathrm{ep},i}}{Q_{\mathrm{D}}} \right|^2 + \left| \left| \frac{T_{\mathrm{ap}}}{T_{\mathrm{p},i}} \right|^2 \cdot S_{\mathrm{eap}} \right|^2} \\ \leq AMP_i \cdot \left| PFA_{ij} \right|$$

$$AMP_{i} = \begin{cases} 2.5 \cdot \sqrt{\frac{10}{(5 + \xi_{ap})}}, & \frac{T_{p,i}}{T_{C}} = 0 \\ \text{linear between } AMP_{i} \left(\frac{T_{p,i}}{T_{C}} = 0\right) \text{ and } AMP_{i} \left(\frac{T_{p,i}}{T_{C}} = 0.2\right), & 0 \le \frac{T_{p,i}}{T_{C}} \le 0.2 \\ \frac{10}{\sqrt{\xi_{ap}}}, & \frac{T_{p,i}}{T_{C}} \ge 0.2 \end{cases}$$



#### **METHOD 2: SIMPLE BUT CONSERVATIVE**

- Only one mode considered
- Amplification taken at resonance
  - Component damping @ 2%
- Simplified linear mode shape assumed if unknown
- No reduction for structural inelasticity unless verified by pushover
  - Conservative!
  - No need to know much about the structure, but you pay for it

$$F_{\rm ap} = \frac{\gamma_{\rm ap} \cdot m_{\rm ap} \cdot S_{\rm ap}}{q_{\rm ap}'}$$

$$S_{\rm ap} = AMP \cdot PFA$$

$$PFA = \Gamma_1 \cdot \varphi_{1,ap} \cdot \frac{S_e(T_{p,1},\xi_{p,1})}{q_D} \ge \frac{S_\alpha}{F_A}$$

$$\varphi_{1,ap} = \left(\frac{z}{H}\right)$$
, if mode unknown

 $q_{\rm D}{}' = 1$ , if structural inelasticity unverified

#### **METHOD 3: FUSE FOR THE WIN**

- Only one mode considered
- Amplification taken at resonance
  - Component damping @ 2%
- Fuse of certified ductility & strength diminishes resonance effects
- **Disengage** from structural & component characteristics
  - Highly reliable
  - Low design accelerations (component remains functional)
  - Low anchorage forces transmitted to structure
  - Higher reliability enforced at ductility: Certify for  $\mu_D \cdot \gamma_{ap}$ , use  $\mu_D$



$$S_{\rm ap} = AMP \cdot PFA$$

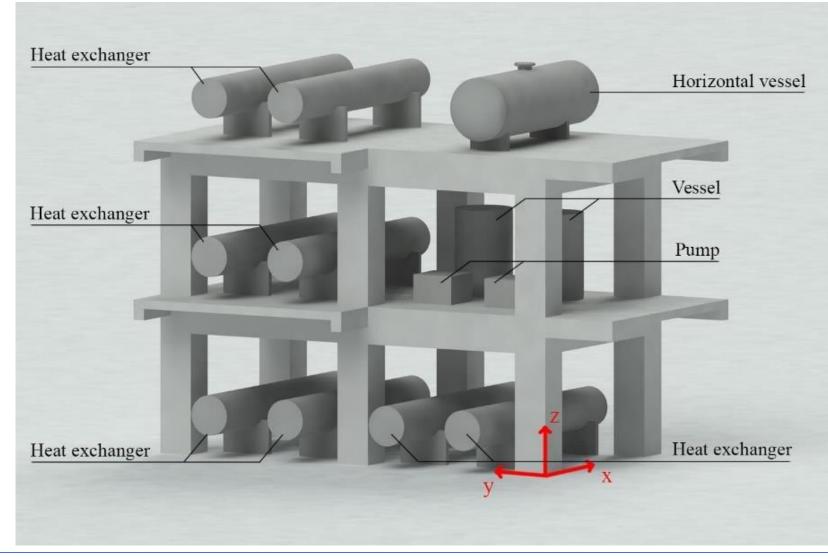
$$AMP = max\left\{ 1.30, 0.60 + \frac{1.40}{(\mu_{\rm D} - 1.0)} \right\}$$

 $\mu_{\rm D} \ge 1.50$ 



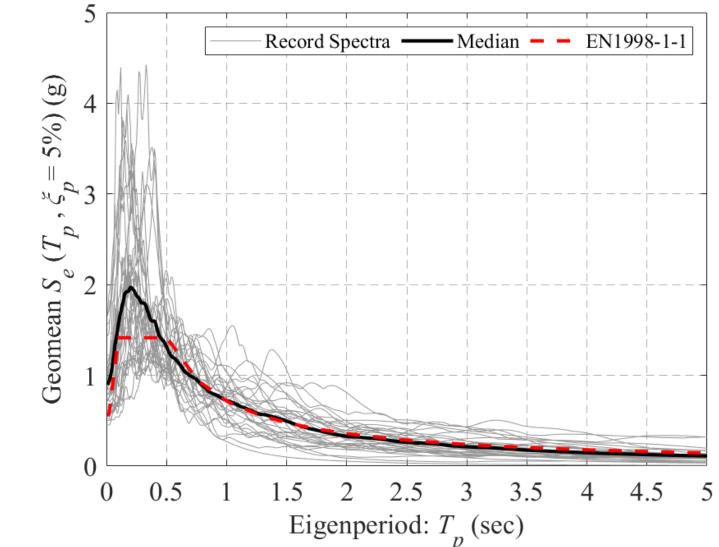
#### AN EXAMPLE CASE STUDY

- Equipment-supporting RC-MRF, 8x15m plan
- Typical refinery building
- Located in Elefsina, Greece,  $a_g = 0.24g$ ,  $S_{\alpha,ref} = 0.71g$
- Consequence Class 3a
  - Perf. factor 1.75
  - $S_{\alpha,ref} = 1.24g$  for 2,500 years
- Ductility Class 2 (moderate!)
- Tp,1x ≈ Tp,1y = 0.2s
- Heavily overdesigned for fireproofing
- Elastic response!





- Important components
  - $-\gamma_{ap}$  = 1.5
  - Any additional overstrength in anchorage (i.e 4 vs 3 bolts) disregarded
- Use RHA for accurate assessment of demands
- 30 "ordinary" records
- Selected to be compatible with 2%/50yr hazard via Conditional Spectrum
- Conditioned to match AvgS<sub>a</sub>(0.1–1sec)



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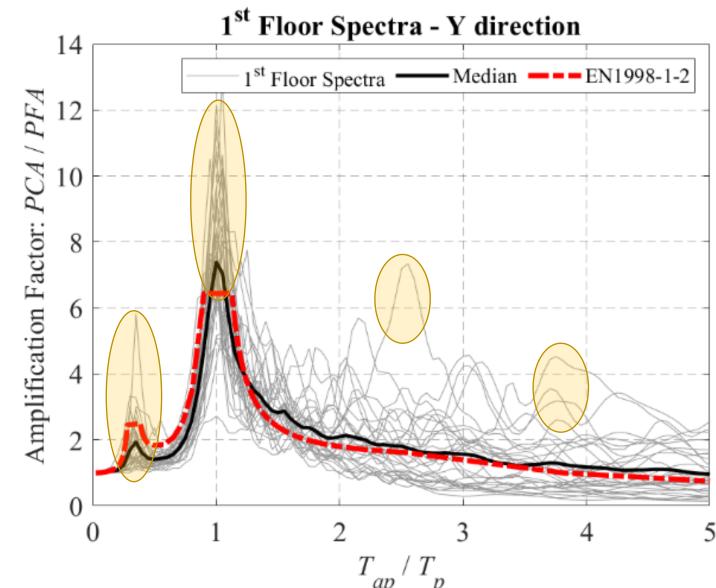
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- Excellent accuracy
  - Max AMP = 7.07
  - Some records go higher
  - Still ok
- Higher modes also captured
- Localized **peaks** at higher normalized periods can happen
- Impossible to predict without RHA
- Code is not magic!
- Still, pretty rare events



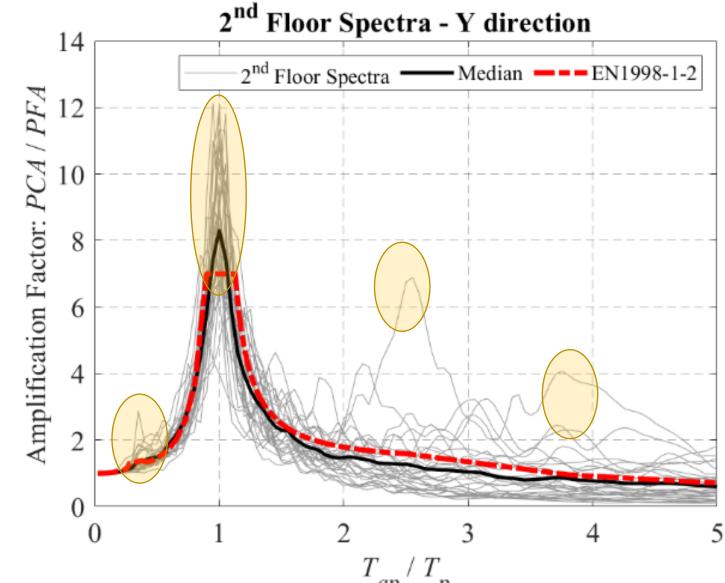
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#### **METHOD 1: FLOOR SPECTRA 2**

- Excellent accuracy
  - Max AMP = **7.07**
  - Some records go higher
  - Still ok
- Higher modes also captured
- Localized **peaks** at higher normalized periods can happen
- Impossible to predict without RHA
- Code is not magic!
- Still, pretty rare events



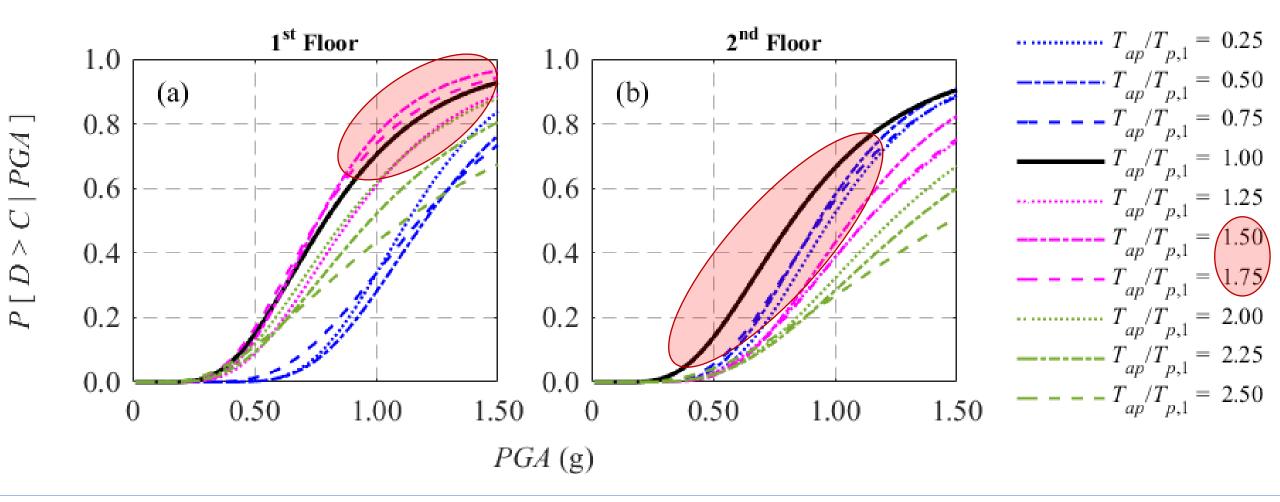
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#### **METHOD 1: FRAGILITIES**

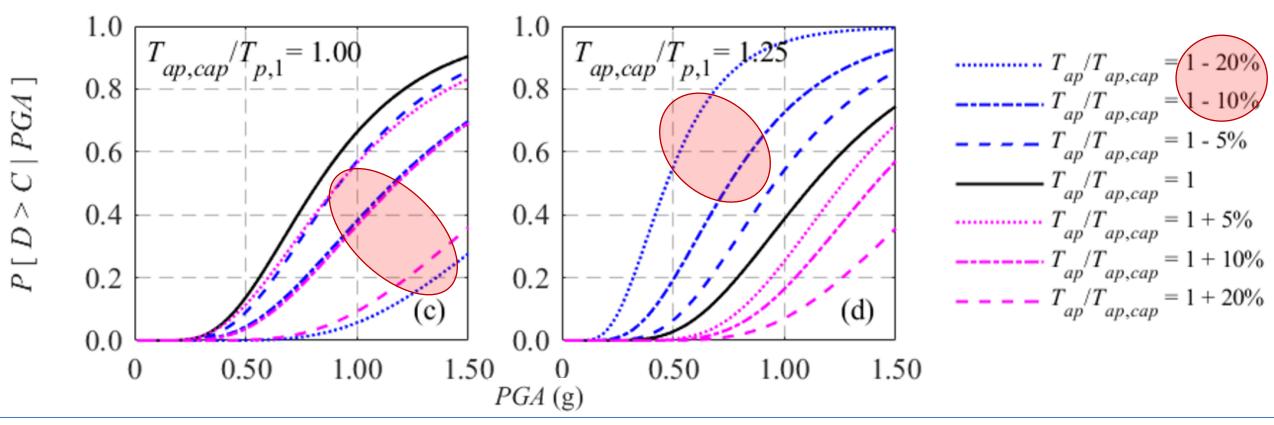
• If you know everything, Method 1 is excellent (minus some exceptions)





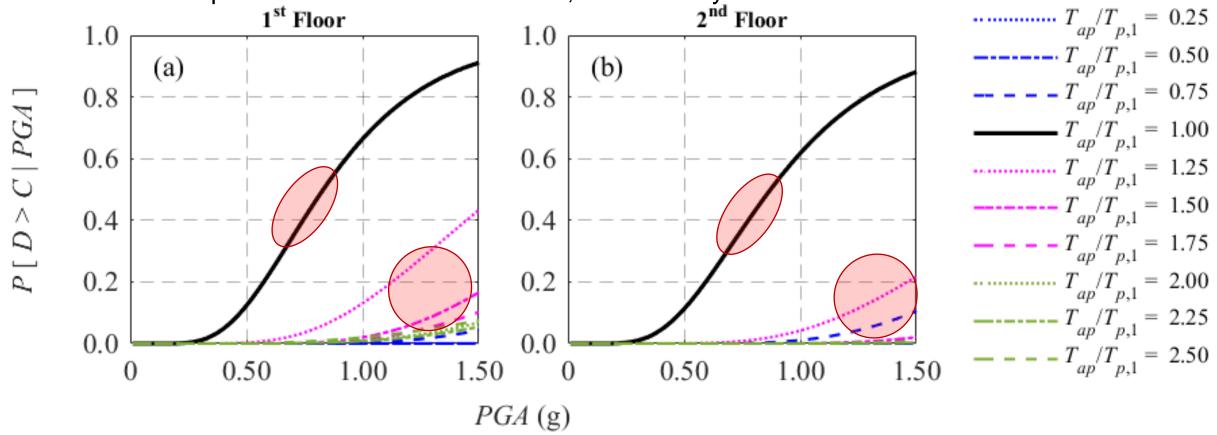
### **METHOD 1: FRAGILITIES**

- If you thought you were at resonance and you are not, then you are ok! (conservative)
- If you thought you were away but true period is close to resonance, you are in trouble
- So, how sure are you of the actual structure & component periods?





- Once you assume resonance everywhere, everything is super-conservative
- Cost = 1-2 bolts more, for most components
- When component is indeed in resonance, same safety as Method 1



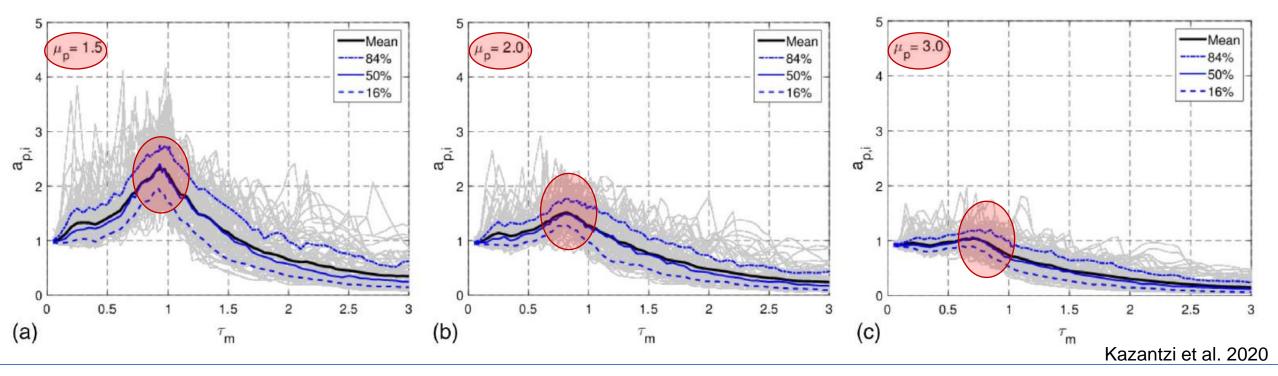
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### **METHOD 3: CONCEPT**

- Four **nominal** ductility levels for fuse:  $\mu_D = \{1.5; 2.0; 2.5; 3.0\}$
- Important elements, manufacturer must certify for 1.5  $\mu_{\rm D}$
- Increasing nominal  $\mu_D$  is not meant to increase safety, only  $\gamma_{ap} = 1.5$  does this
- Increasing nominal  $\mu_D$  decreases forces & accelerations (i.e., protect functionality)



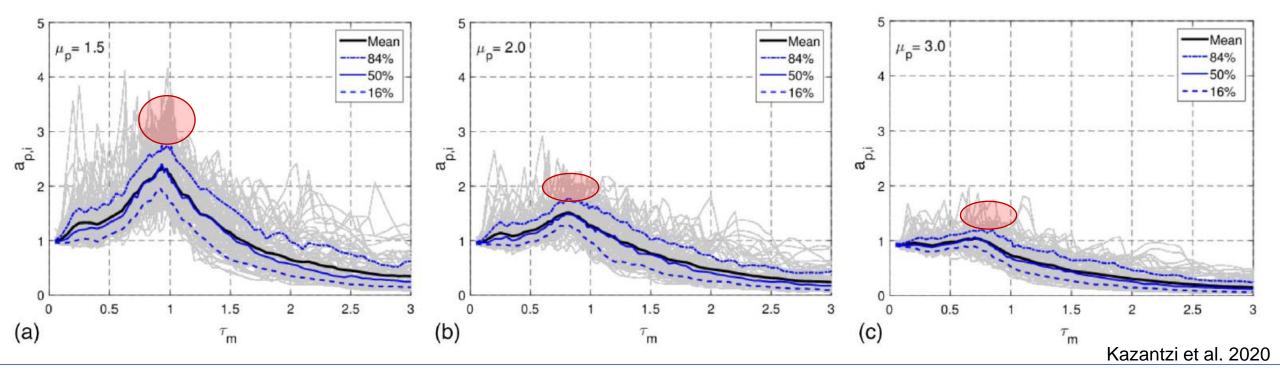
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#### **METHOD 3: CONCEPT**

- This decrease is substantial (~90% values used):
  - $-\mu_{\rm D} = 1.5 => AMP = 3.4$
  - $\mu_{\rm D} = 2.0 \Rightarrow AMP = 2.0$
  - $\mu_{\rm D} = 3.0 \Rightarrow \text{AMP} = 1.3$

If you need lower AMP, use base isolation!

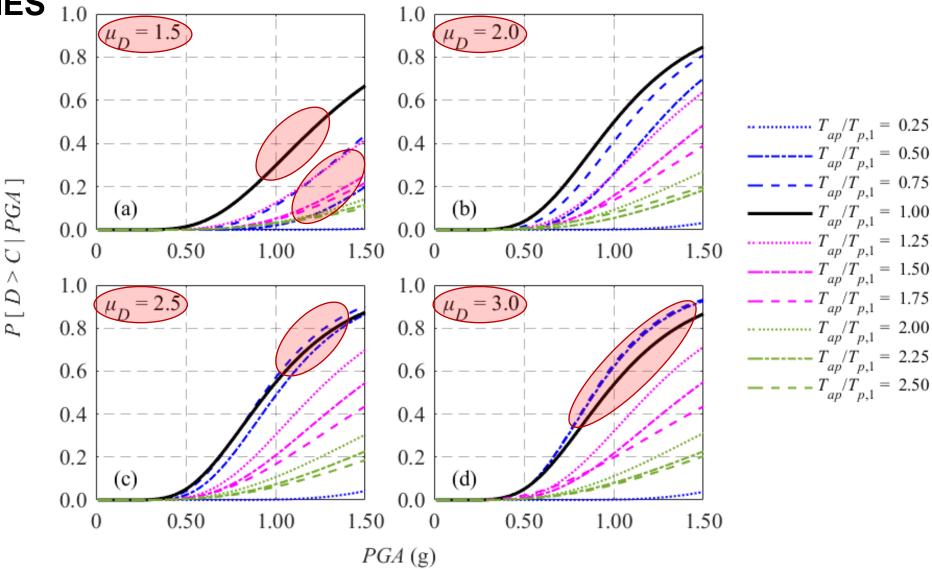


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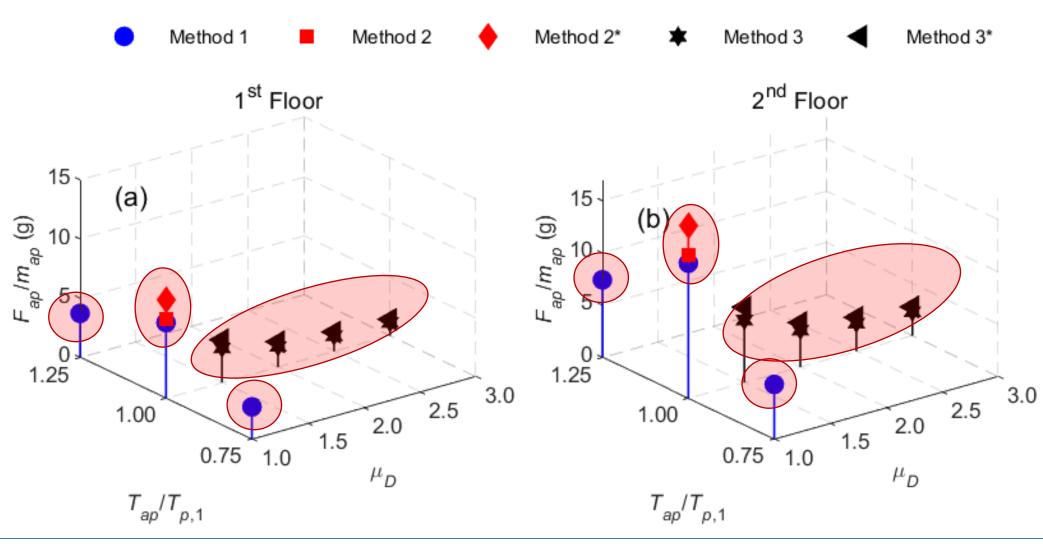
### **METHOD 3: FRAGILITIES**

- In resonance => a bit safer than Method 1
- Out of resonance => conservative
- $\mu_{\rm D} = 1.5$  more conservative
- Higher ductilities provide similar levels of safety
- Minor exceedances for  $\mu_{\rm D} = \{2.5; 3.0\}$
- Remember, you know only component mass
- ....but you certified the fuse!





- 2\* and 3\* = approx. mode shape
- If out of tune, Method 1 is best, Method 2 is too conservative
- If in tune, all methods work
- If you have no idea, Method 3 always delivers
- ...but who makes the fuse?



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#### CONCLUSION

- All three methods are **viable**
- Make sure you **respect** their assumptions:
  - Do not assume you know the **period** because your model provides it!
  - Do not assume any piece of steel can become a **fuse**
  - In ductile design, **overstrength** can be the enemy
- Have fun and stay safe with EN1998-4:2022!

